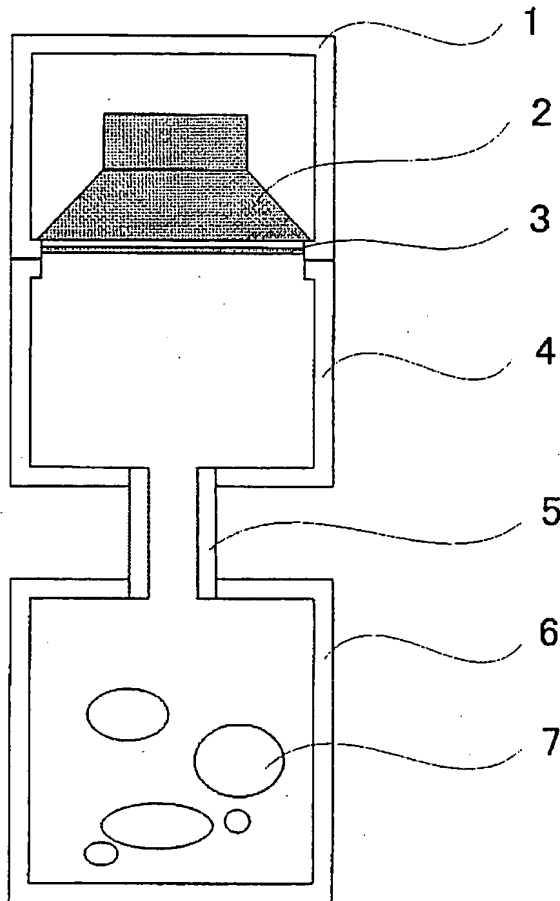


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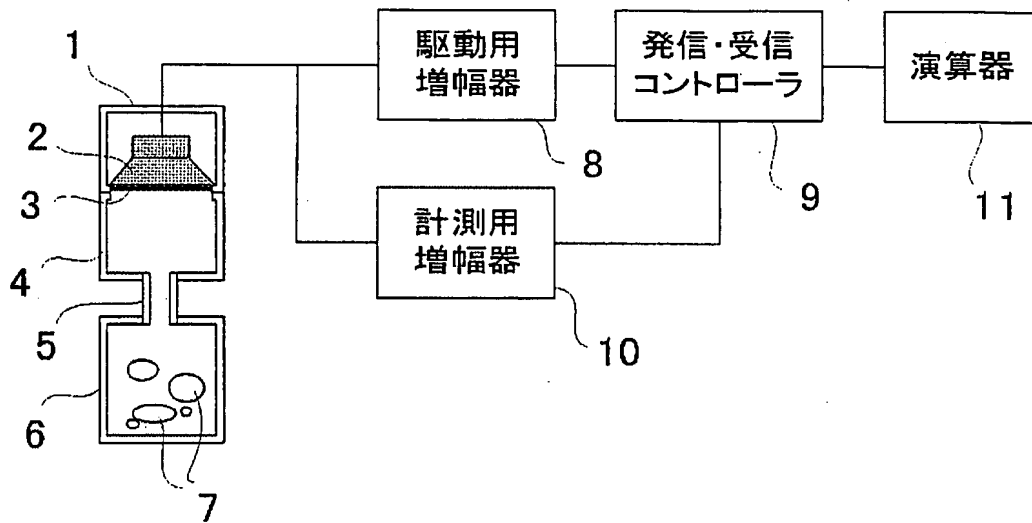
[図1]



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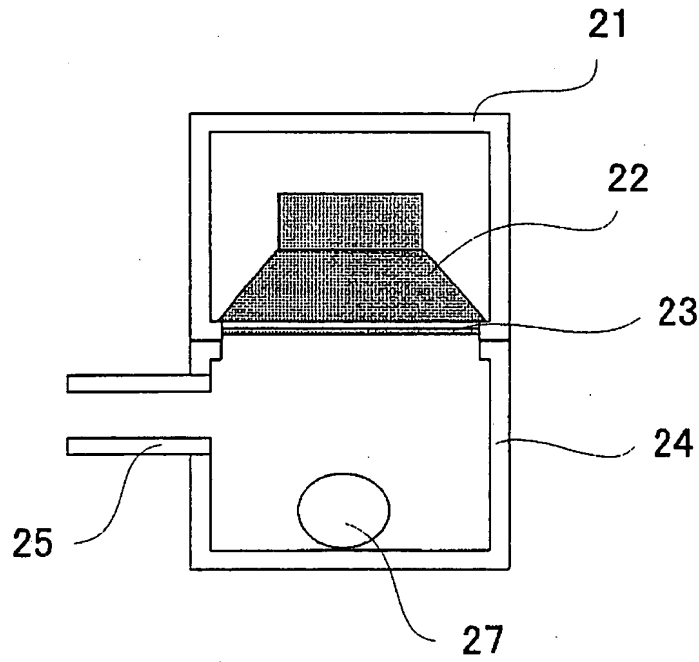
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[図2]



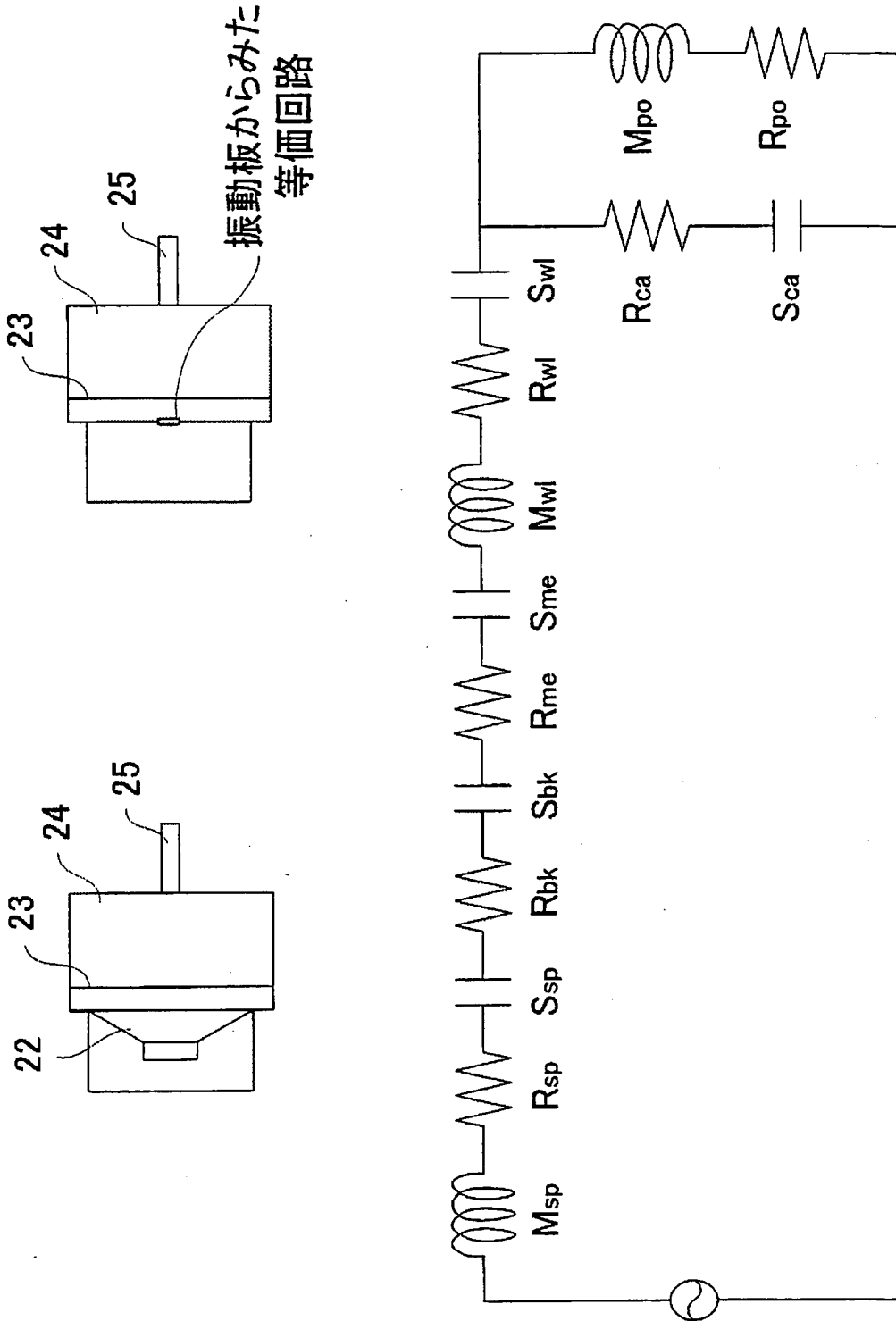
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[図3]



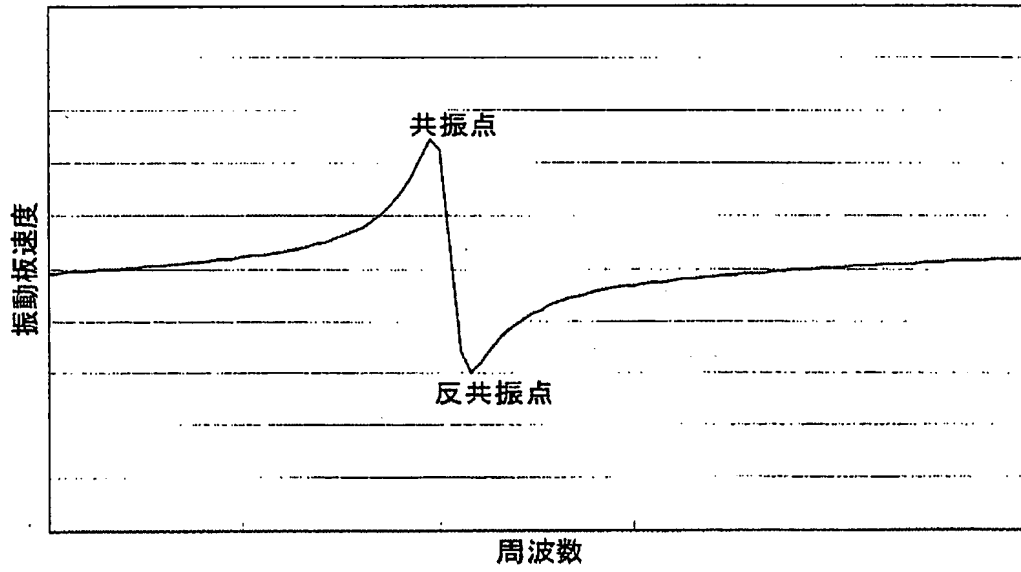
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[図4]



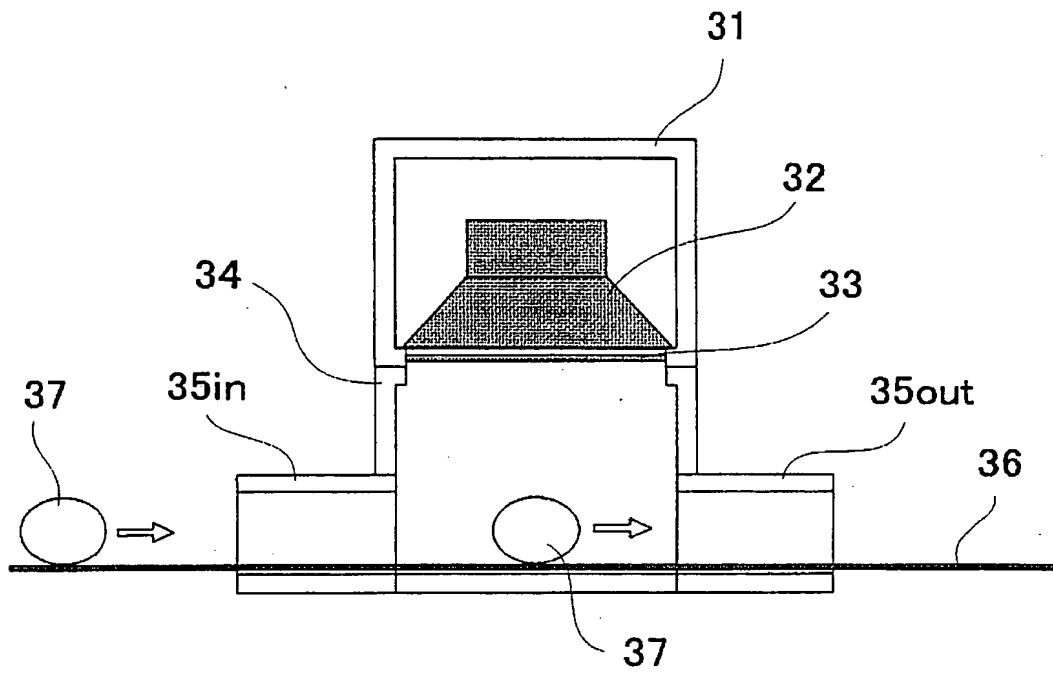
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[図5]



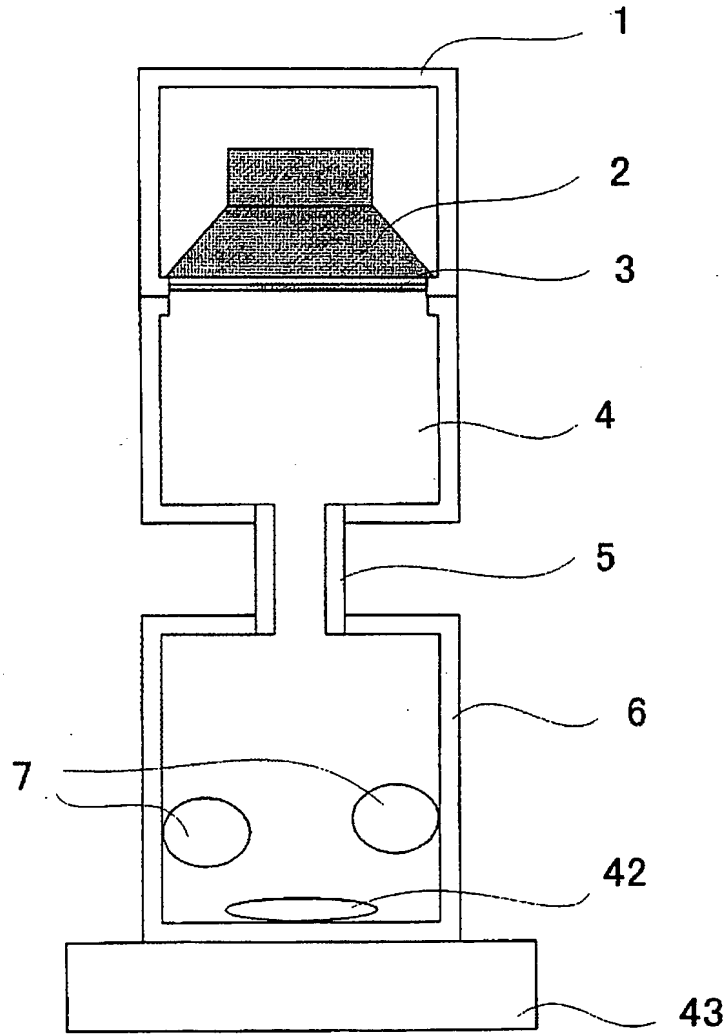
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[図6]



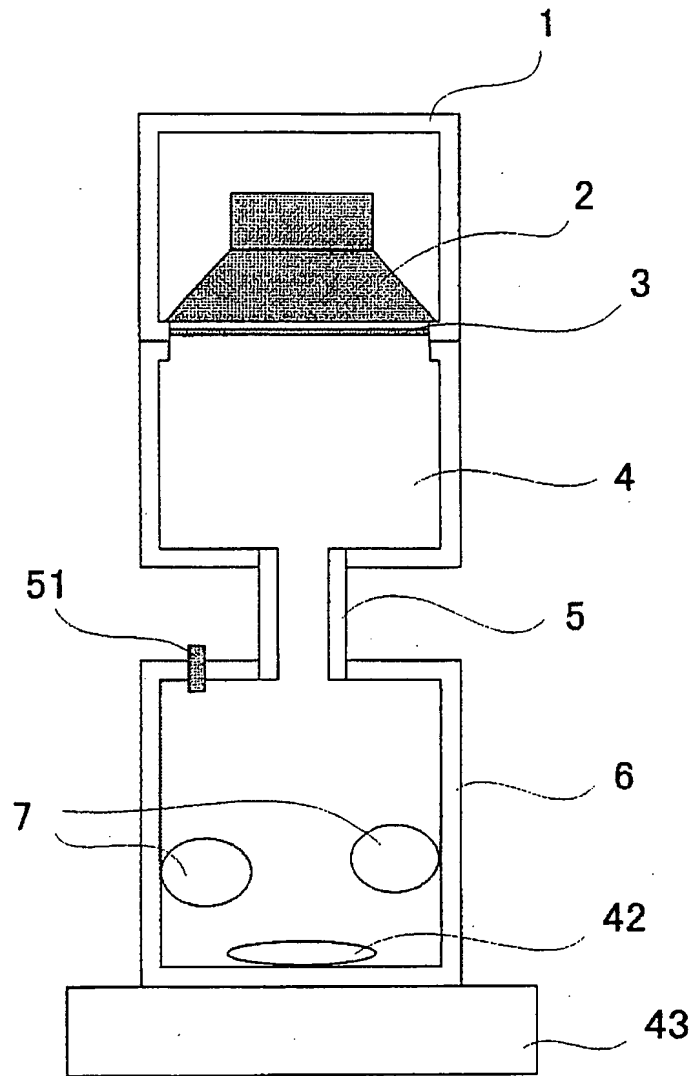
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[図7]



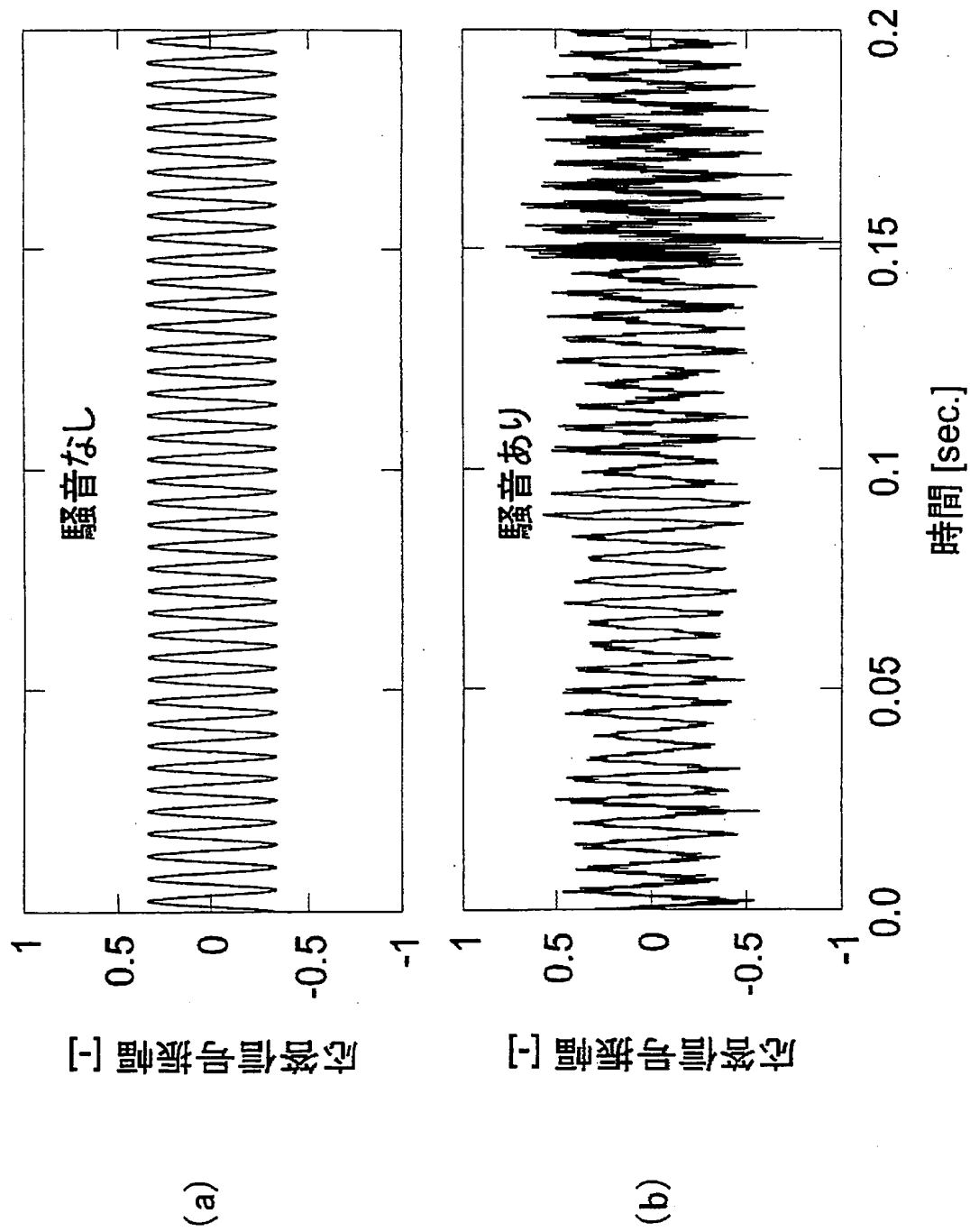
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[図8]

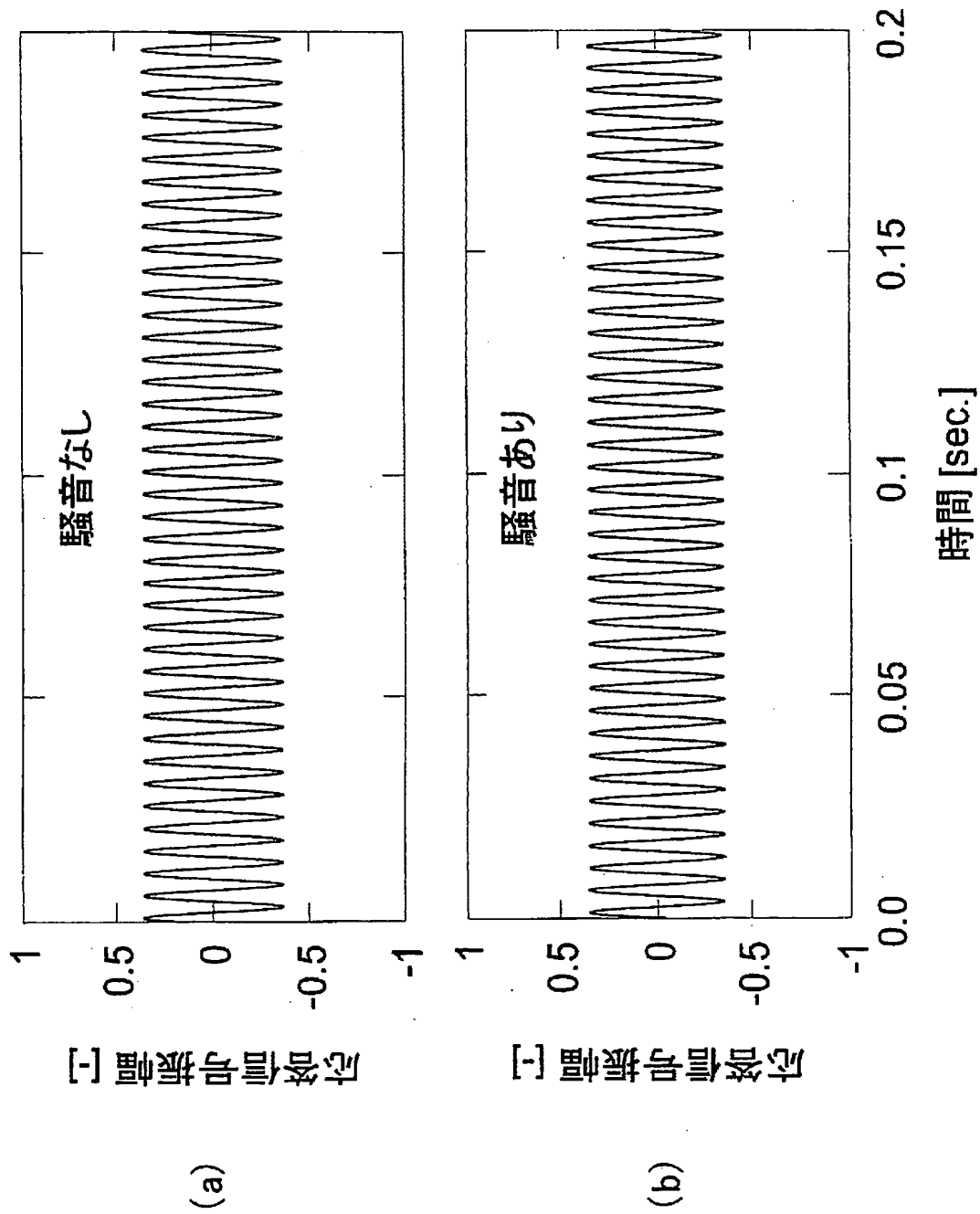


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[図9]



[図10]



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[図11]

表1

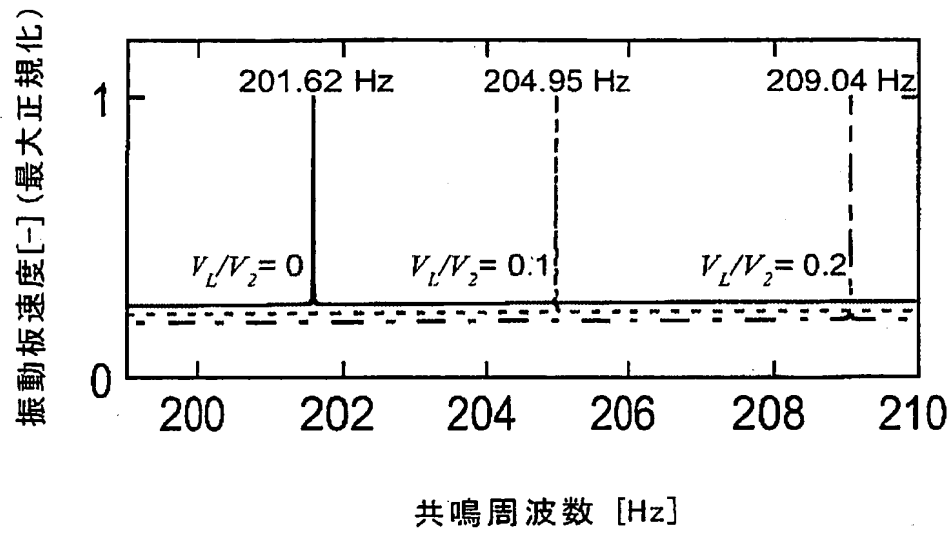
	マイクロフォンを用いた場合		定電流駆動型増幅器を用いた場合	
	無騒音	騒音下	無騒音	騒音下
標本数	100	100	100	100
変動係数 [%]	0.00173	0.254	0.0238	0.0256

*変動係数 (%) : 平均値に対する標準偏差の百分率

The diagram illustrates the electrical circuit and mechanical components of a magnetic field measurement system. The circuit is powered by an AC source i_F . It consists of several series and parallel branches. The main series branch includes an inductor M_{sp} , a resistor R_{sp} , a capacitor S_{sp} , a resistor R_{bk} , a capacitor S_{bk} , a resistor R_{md} , a capacitor S_{md} , an inductor M_{md} , a resistor R_{md} , and a capacitor S_{md} . A parallel branch contains a resistor R_{cd} and a capacitor S_{cd} . Another parallel branch contains an inductor M_{po} and a resistor R_{po} . A final parallel branch contains a capacitor S_{c2} and a resistor R_{c2} . A schematic of the probe assembly is labeled 2a, with components 4, 5, and 6 corresponding to parts of the circuit.

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[図13]



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